



1 **Feasibility of three-dimensional density tomography**
2 **using dozens of muon radiographies and Filtered**
3 **BackProjection for volcano**

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9 **Abstract.** This study is the first trial to apply the method of filtered backprojection
10 (FBP) method to reconstruct three-dimensional (3D) bulk density images via cosmic-ray
11 muons, We also simulated three-dimensional reconstruction image with dozens of
12 muon radiographies using FBP method for a volcano and evaluated its practicality.

13 FBP method is widely used in X-ray and CT image reconstruction but has not been
14 used in the field of muon radiography. One of the merits to use FBP method instead of
15 ordinary inversion method is that it doesn't require an initial model, while ordinary
16 inversion analysis need an initial model.

17 We also added new approximation factors by using data on mountain topography into
18 existing formulas to successfully reduce systematic reconstruction errors. From a
19 volcanic perspective, airborne radar is commonly used to measure and analyze
20 mountain topography.

21 We tested the performance and applicability to the model of Omuroyama, a
22 monogenetic scoria cone located in Shizuoka, Japan. As a result, it was revealed that
23 the density difference between the original and reconstructed images depended on the
24 number of observation points and the accidental error caused by muon statistics
25 depended on the multiplication of total effective area and exposure period.

26 Combining above all things, we established how to evaluate an observation plan for
27 volcano using dozens of muon radiographies.

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29 **1 Introduction**

30 **1.1 Muon radiography and its principle**

31 Muon radiography is a method that can be used to make a map of the inner bulk
32 density structures of large objects such as volcanoes, archeological targets, and so on,
33 using secondary cosmic-ray muons. These muons are generated by the interactions
34 between high energy primary cosmic-rays (the main component is proton) and nuclei in
35 the atmosphere. The flux, energy spectrum, and the zenith angle dependence of
36 secondary cosmic-ray muons have been well researched (e.g. Dorman, 2004; Honda et
37 al., 2004; Patrignani et al., 2016; Nishiyama et al., 2016). Also their behavior
38 including energy loss in the various material have been investigated (Groom et al.,
39 2001). Therefore, when we assume "density length", which is the integration of
40 multiplication of density and material thickness, we can evaluate the number of
41 penetrating muons. Muon detection technology also have been developed in the field of



42 particle physics and cosmic-ray physics. To make a bulk density map, we need to
43 measure not only the counts of penetrating muons from the target, but also the
44 direction. For example, nuclear emulsion films (Morishima et al., 2017), hodoscope by
45 scintillating plastic bars (Jourde et al., 2013), glass resistive plate chambers (Ambrosino
46 et al., 2015), multi-wire proportional chambers (Oláh et al., 2018) are capable to do that.
47 By implementing these muon detectors around the target, we can get the penetrating
48 muon flux for each direction from the detector, then by comparing to initial muon flux,
49 we also get the attenuation of muons for each directions. By using the topographic data
50 of the target, it is possible to lead the two-dimensional averaged bulk density from the
51 muon attenuation and the path length of the target material.

52 The principle of X-ray radiography and muon radiography is very similar. There are
53 two significant differences between these two methods: the first is the attenuation
54 length. Typical X-ray beam can penetrate the material less than 1 meter water
55 equivalent. On the other hand, some muons can penetrate the order of kilo meter water
56 equivalent because their kinetic energy is very high. The second difference is the origin
57 of the source. The source of cosmic-ray muons is completely environmental and we can't
58 control the flux while X-ray beam are generated by accelerating the electron artificially.
59 Typically, the number of observed muons is much smaller than ordinary X-ray
60 radiography.

61 The first significant result for volcanology was the two-dimensional bulk density
62 imaging of the shallow conduit in Mt. Asama by Tanaka et al., 2007a. Several
63 observation have been done after this research (e.g. Tanaka et al., 2007b; Lesparre et al.,
64 2012; Tanaka et al., 2014).

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66 **1.2 Three-dimensional bulk density imaging**

67 The internal structure of volcanoes gives important information for volcanology. For
68 example, the shape of shallow conduit affects the eruption dynamics (Ida, 2007).
69 However, muon radiography by only one direction makes just a 2D image, and this
70 density is average of material along the muon path direction. Therefore, if we find some
71 contrast in 2D density image, we can't distinguish the actual position of this density
72 anomaly along muon path direction. To observe the real conduit shape, it is necessary to
73 get the density image from different directions to reconstruct the three-dimensional
74 bulk density image.



75 Tanaka et al. (2010) attempted to observe the target from two directions in Mt. Asama.
76 Nishiyama et al. (2014, 2017) conducted a 3D density analysis in Showa-Shinzan Lava
77 Dome, combined with gravity observation data, which is also sensitive to density.
78 Jourde et al. (2015) evaluated this joint-inversion method between muon radiography
79 and gravity, and they observed and conducted 3D density analyses by using three-point
80 muon radiography and gravity data (Rosas-Carbajal et al., 2017). These previous
81 studies required prior information internal density distribution because of insufficient
82 observation data, and they were performed using inversion technique.

83 In this study, we propose the application of a 3D density-reconstruction analysis method using
84 filtered back projection (FBP), which does not require prior information. This method is applied
85 to X-ray computed tomography (CT). However, muon radiography differs from X-ray CT in three
86 points. First, there is a constraint on the number of observation points and position. In X-ray CT,
87 there are hundreds of observation points, and each position is controllable. However, for muon
88 radiography, we can only use several dozen points, and the positions are limited because of
89 topography. Second, the cosmic-ray muon attenuation flux is not a simple exponential. Therefore,
90 the influence of muon statistical error depends on the results of 3D density, which is not trivial. Third,
91 in the case of muon radiography typically the amount of signal is much less than X-ray, because the
92 source of cosmic-ray muon is completely environmental. Therefore, it is important to study the
93 features of FBP method in the case of realistic observations with various number of muon
94 radiographies. So we should consider not only the reconstruction error by FBP method, but also how
95 the error of muon statistics propagates to the final image.

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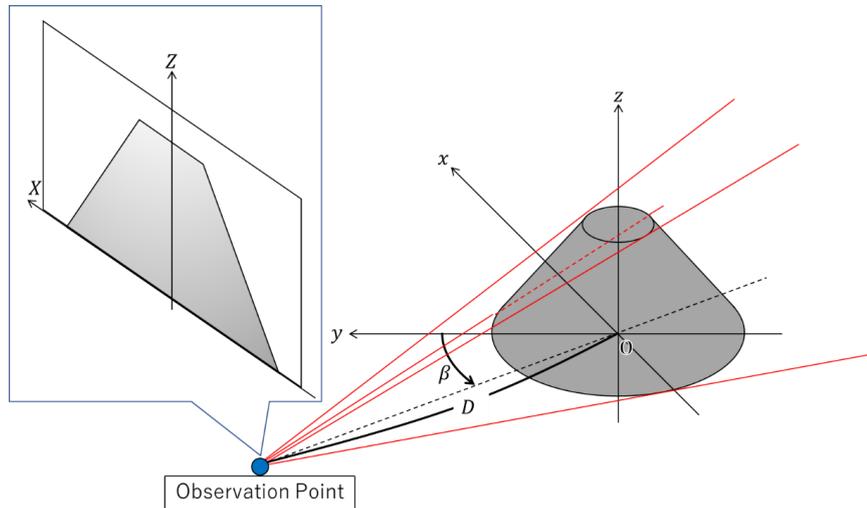
99 2 Method

100 The Radon transform is used to obtain projection images from all directions with
101 respect to a density distribution. In muon radiography, this corresponds to acquiring
102 observation data on density length from all directions. For three dimensions, the Radon
103 transform $p(X, Z, \beta)$ of an object with density $\rho(x, y, z)$ is given by the following:

$$104 \quad p(X, Z, \beta) = \int \rho \left(-D \sin \beta + \frac{t}{\sqrt{1+X^2+Z^2}} (X \cos \beta + \sin \beta), D \cos \beta + \frac{t}{\sqrt{1+X^2+Z^2}} (X \sin \beta - \right. \\ 105 \quad \left. \cos \beta), Z \right) dt, \quad (1)$$



106 where x , y , and z are the positions in a 3D volume; X and Z are the tangents of
 107 azimuth and elevation angle values, respectively; β is the observation point position at
 108 a counterclockwise angle with respect to the y axis, and D is the distance between the
 109 observation point and the origin. Figure 1 shows the geometric definition for these
 110 parameters.
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Figure 1: A schematic of Radon Transform and the definition of parameters x, y, z, X, Z, β and D .

117 In a 3D case, if observation data have an elevation angle and observation points only
 118 exist on the circumference, a complete inverse Radon transform does not exist.
 119 Therefore, approximation is needed. Feldkamp (1984) proposed one of the best methods
 120 to approximate a solution with a small elevation angle in two dimensions. This
 121 approximation is written as follows:

$$122 \quad \rho(x, y, z) = \frac{1}{2} \int_0^{2\pi} d\beta \int_{-X_M}^{X_M} dX \frac{D}{L_2^2 \sqrt{1 + X^2 + Z^2}} p(X, Z_0, \beta) h(X_0 - X), \quad (2)$$

123 where $Z_0 = z / (D - x \sin \beta - y \cos \beta)$, $L_2 = \sqrt{1 + Z_0^2} (D + x \sin \beta - y \cos \beta)$, $X_0 = (x \cos \beta +$
 124 $y \sin \beta) / L_2$, and $h(X)$ is a Ram-Lak filter (Ramachandran and Lakshminarayanan,
 125 1971). A feature of this method is that it does not require the shape or initial model of
 126 the object. However, when there is a density change in the vertical direction, the
 127 accuracy of the approximation decreases. In many examples of volcanic muon



128 radiography, we obtain the shape of the volcano by using other methods; therefore, the
 129 influence of changes in the shape can improve the accuracy of the approximation. To
 130 estimate the elevation angle, we use the ratio of the path length of the observed muon
 131 $q(X, Z_0, \beta)$ to the approximation of $q_h(X, Z_0, \beta)$ (see Fig. 2), which can be written as
 132 follows:

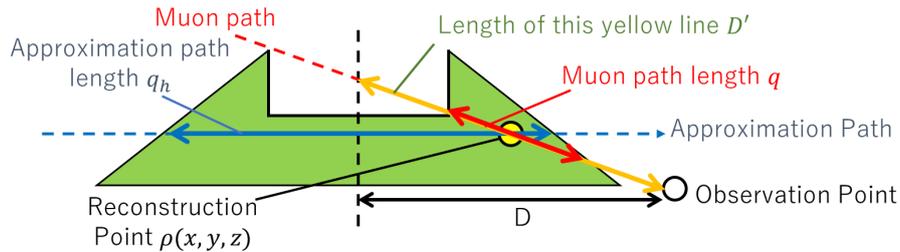
$$133 \quad p'(X, Z, \beta) = \frac{q_h(X_m, z, \beta_n)}{q(X_m, Z_{0n}, \beta_n)} p(X, Z, \beta), \quad (3)$$

134 where $p'(X, Z, \beta)$ is the approximation of the density length for the inverse Radon
 135 transform. Finally, the reconstruction calculation formula can be written as follows:

$$136 \quad \rho(x, y, z) = \sum_{n=1}^N \delta\beta_n \sum_{m=1}^M \delta X_m \left(1 - \frac{X_m}{D(\beta_n)} \delta D_n\right) \frac{D(\beta_n)}{L_2^2 \sqrt{1 + X_m^2}} \frac{p(X_m, Z_{0n}, \beta_n)}{q(X_m, Z_{0n}, \beta_n)} q_h(X_m, z, \beta_n) h(X_0 - X_m), \quad (4)$$

137 where m, n is the index of X, β , respectively. We name this approximation “path length
 138 normalization approximation (PLNA).”

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 143 Figure 2: Path length schematic and the approximation difference between Feldkamp
 144 approximation and path length normalization approximation. In Feldkamp
 145 approximation, the approximation density length is $p' = D/D' \times p$. In path length
 146 normalization, the approximation density length is $p' = q_h/q \times p$.

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150 3 Simulation

151 In this section, we describe the specific components of the simulation calculation. The
 152 simulation calculation is divided into the following four steps:



- 153 1. Parameter setup
- 154 2. Simulation calculation of the observed muon counts
- 155 3. Reconstruction calculation using data created in Step 2
- 156 4. Calculations for evaluating the reconstruction results
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159 3.1 Parameter setup for target and detector

160 We simulated and reconstructed the density structure of Omuroyama, which is located in Shizuoka,
161 Japan. We chose this volcano for two reasons. First, this volcano is easily observable from all
162 directions because there are no large structures around the surrounding muon shields
163 in a topographical view. Second, there are no occurrences of muon radiography for these
164 large scoria hills. Omuroyama is a large scoria hill. We base the internal structural
165 model of the large scoria hill on observations at the time of its formation (Luhr et al.,
166 1993). However, there are currently no direct examples of these observations.

167 Figure 3 shows the contour map of the Omuroyama model used in the simulation.
168 We assume that the x axis is in the east–west direction, the y axis is in the north–
169 south direction, and the origin is the summit.

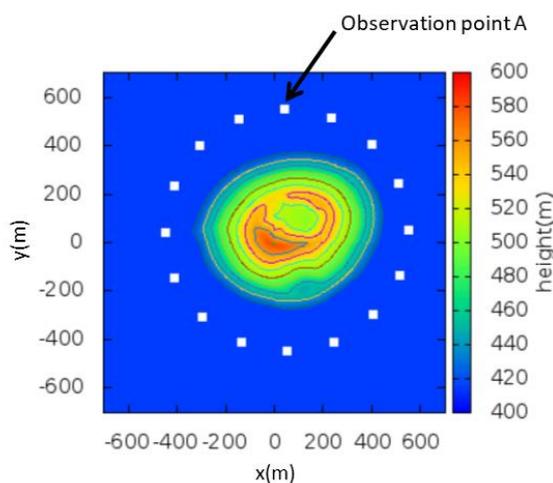
170 We configure the internal density distribution similar to a checkerboard with a side
171 length of 100 m and a density of 1 and 2 g/cm³. We presume that the first internal
172 density distribution is defined as the original image and is expressed as $\rho^{ori}(x, y, z)$.

173 The field of view was set to -2 to 2 (-63.4 to 63.4 in degrees) horizontally and 0 to 1 (0
174 to 45 in degrees) vertically, and the angular resolution was set to 0.04 (2.3 in degrees) in
175 tangent. The observed muon statistics affect the density reconstruction error: the
176 number of muons observed is proportional to the effective area of the device and the
177 exposure period. The total effective area and exposure period ST of all muon devices
178 was set as $1000 \text{ m}^2 \cdot \text{days}$. For example, when the number of observation points is 16,
179 each ST per point is $1000/16 = 62.5 \text{ m}^2 \cdot \text{days}$.

180 All observation points were assumed to be on the circumference of radius $D = 500 \text{ m}$
181 placed on the center $(x, y) = (50 \text{ m}, 50 \text{ m})$ of the mountain. The position of the
182 observation points on the circumference is equal to the rotation angle from the reference
183 line. The position β (rad) of the observation point is defined counterclockwise from the
184 straight line parallel to the y axis and passes through the center $(x, y) = (50 \text{ m}, 50 \text{ m})$
185 of the mountain. The value of β , on which the observation point is placed, must always be
186 one at $\beta = 0$, with the rest arranged at equal intervals along the circumference. For



187 example, for the 16 observation point case, the position of the observation point is $\beta_n =$
188 $\frac{2\pi}{16}n$ ($n = 0, 1, \dots, 15$). The figure 3 also shows the observation point arrangement when
189 there are 16 observation points.
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193 Figure 3: The mountain body model and observation points (when the number of
194 observation points is 16). Based on the Omuroyama Digital Elevation Model (DEM)
195 data from the Geospatial Information Authority of Japan. All areas with altitudes of
196 420 m or less are adjusted to an altitude of 420 m. The resolution is 5 m. The coordinate
197 origin is at the summit. Observation points are located on the circumference with a
198 radius of 500 m centered on a point that was moved $x = 50$ m and $y = 50$ m from the
199 summit.
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203 3.2 Simulation calculation of muon count observation

204 The simulation calculation of the observed number of muons is mainly performed in
205 the following procedures:

- 206 1. Calculate the density length $p(X, Z, \beta)$ from $\rho^{ori}(x, y, z)$ for each observation
207 direction viewed from the observation point.
- 208 2. Calculate the theoretical muon flux $F_0(X, Z, \beta)$ by using a previously prepared



209 relationship between the muon flux, elevation angle, and penetration density length.
210 We used the cosmic-ray muon flux model of Honda et al. (2004) and the muon energy
211 attenuation of Groom et al. (2001) for the calculations made here.

212 3. Calculate the theoretical muon count observation $N_0(X, Z, \beta)$ by multiplying
213 $F_0(X, Z, \beta)$ the device area S of the observation period T and the solid angle of spatial
214 decomposition in the observation direction.

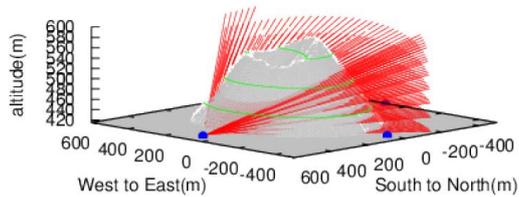
215 Figure 4a shows the observation state at observation point A in figure 3, and Fig. 4b
216 shows the theoretical muon count observation $N_0(X, Z, 0)$ at that time. $N_0(X, Z, \beta)$ is the

217 It is not suitable to use muon flux table in the region of 10 meter water equivalent or
218 less because of small change. To avoid this region, we did not use this data when the
219 path length $q(X, Z_0, \beta)$ is 10 m or less.

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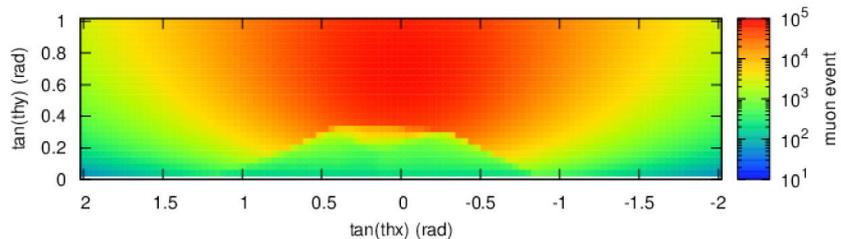
221

222 (a)



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224 (b)



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226 Figure 4: An example of theoretical muon count simulation: (a) the observation state at
227 observation point A; (b) the theoretical muon count observation at that time.

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230 3.3 Reconstruction calculation

231 The reconstruction calculation procedure is as follows:



232 1. Calculate the muon flux $F_0(X, Z, \beta)$ from the muon number $N_0(X, Z, \beta)$, device shape,
233 and observation period.

234 2. Calculate the observed density length $p(X, Z, \beta)$ from $F_0(X, Z, \beta)$, as well as the
235 relationship between the muon flux, elevation angle, and penetration density length.

236 3. In “path length normalization approximation,” calculate path length $q(X, Z_0, \beta)$ and
237 path length $q_h(X, Z_0, \beta)$ on the approximate path from the shape information.

238 4. Calculate the density reconstructed image $\rho^{rec}(x, y, z)$ from the density length
239 $p(X, Z, \beta)$ by using equation (4).

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242 **4 Simulation results and evaluation**

243 **4.1 Systematic error evaluation**

244 We evaluated the systematic error, which is defined as the density difference between
245 the original and reconstructed images at two points. First, we compared the differences
246 between the methods for approximating the elevation angle (i.e., Feldkamp
247 approximation and path length normalization approximation). Second, we quantified
248 the relationship between the observation points and systematic errors.

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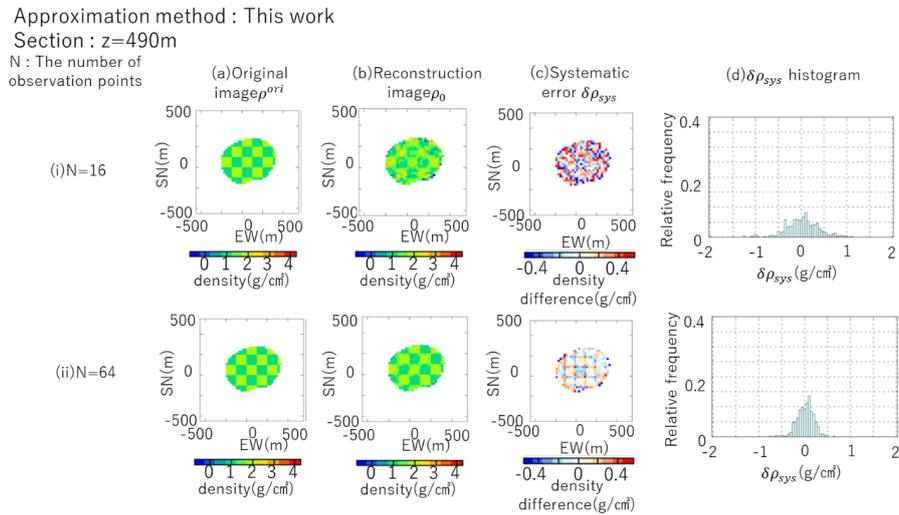
250 **4.1.1 The relationship between the observation points and systematic errors**

251 We modeled scenarios with 4, 8, 16, 32, 64, 128, and 256 observation points. The
252 reconstruction results are shown in Fig. 5. The systematic error $\delta\rho^{sys}(x, y, z)$ was
253 defined as $\delta\rho^{sys}(x, y, z) = \rho^{rec}(x, y, z) - \rho^{ori}(x, y, z)$. To evaluate the systematic error of
254 all the reconstruction results, we calculated the average of $\delta\rho^{sys}(x, y, z)$ over the entire
255 object area as the average value of systematic error μ^{sys} , and the sample standard
256 deviation $\delta\rho^{sys}(x, y, z)$ was defined as the systematic error distribution σ^{sys} .

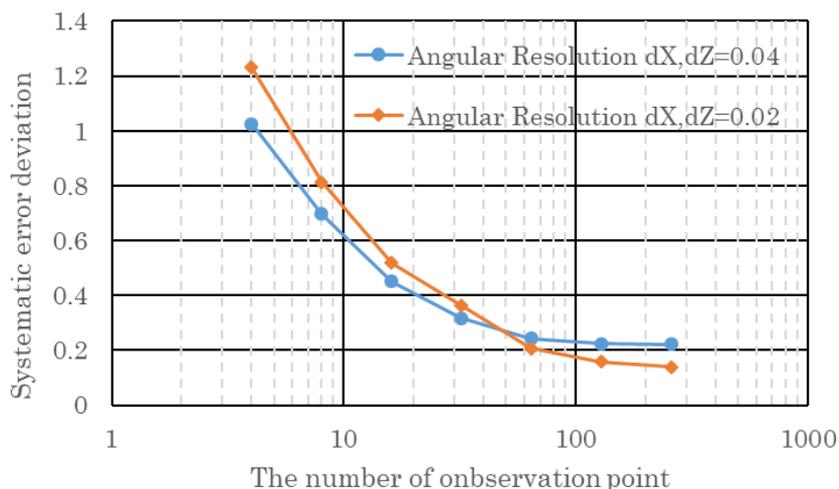
257 The relationship between the number of observation points and systematic error
258 deviation σ^{sys} for the entire mountain body is shown in Fig. 6. As the number of
259 observation points increases, the systematic error decreases. At an angular resolution of
260 0.04, there is almost no change at 64 or more points. At a resolution of 0.02, there is no
261 change with more than 128 points. Therefore, when paying attention to the method of
262 approximating the elevation angle, there are a number of implications when the



263 number of observation points is 64 or more.
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 267 Figure 5: An example of the reconstruction results. All plots were calculated with the
 268 results from path length normalized approximation. The altitude of each section is 490
 269 m. Plots are only from the mountains. (a) Original image: $\rho^{ori}(x, y, z)$; (b)
 270 reconstruction image: $\rho^{rec}(x, y, z)$; (c) systematic error: $\delta\rho^{sys}(x, y, z)$; (d) $\delta\rho_{sys}$
 271 histogram: the relative frequency of systematic error. The mean of this plot is μ^{sys} , and
 272 the sample standard deviation is σ^{sys} .
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275 Figure 6: The relationship between the number of observation points and the systematic
276 error deviation σ^{sys} .

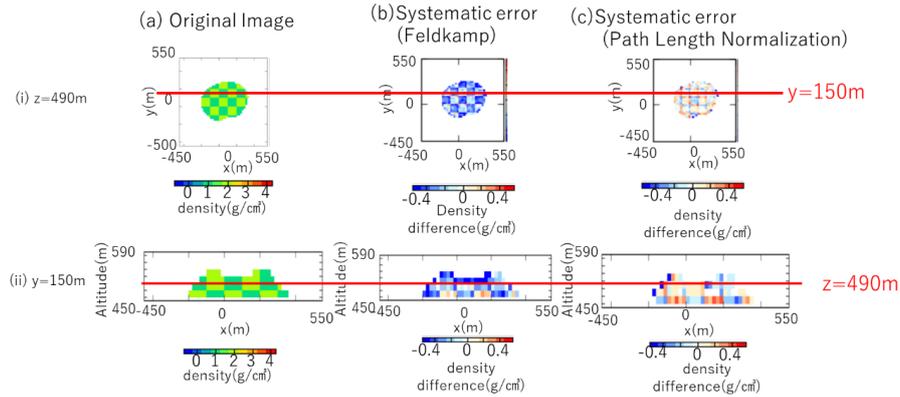
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278 4.1.2 Comparison of Feldkamp approximation and path length normalization approximation

279 We simulated both Feldkamp approximation and path length normalization
280 approximation. Figure 7 shows the reconstruction results of both approximations. In
281 Feldkamp approximation, the average value of the systematic error μ^{sys} was
282 -0.22 g/cm^3 , whereas it was -0.01 g/cm^3 for the path length normalization
283 approximation.

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285



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287 Figure 7: A comparison of Feldkamp approximation and path length normalization
 288 approximation.

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290

291 4.2 Evaluation of accidental errors

292 We also evaluated the accidental error in the reconstruction results. We assumed that
 293 $N_0(X, Z, \beta)$ follows a Poisson distribution. we generate 500 types of values with errors
 294 assigned, according to the Poisson distribution (in the following, referred to as “muon
 295 statistical error”) to $N_0(X, Z, \beta)$. This is referred to as “muon count with statistical error
 296 $N_j^{stat}(X, Z, \beta)$ ($j = 1$ to 500).” Here, the Index “j” represents the trial of different seeds of
 297 random numbers set to $N_j^{stat}(X, Z, \beta)$ for every X, Z , and β .

298 The accidental error $\delta\rho^{acc}(x, y, z)$ was defined as follows:

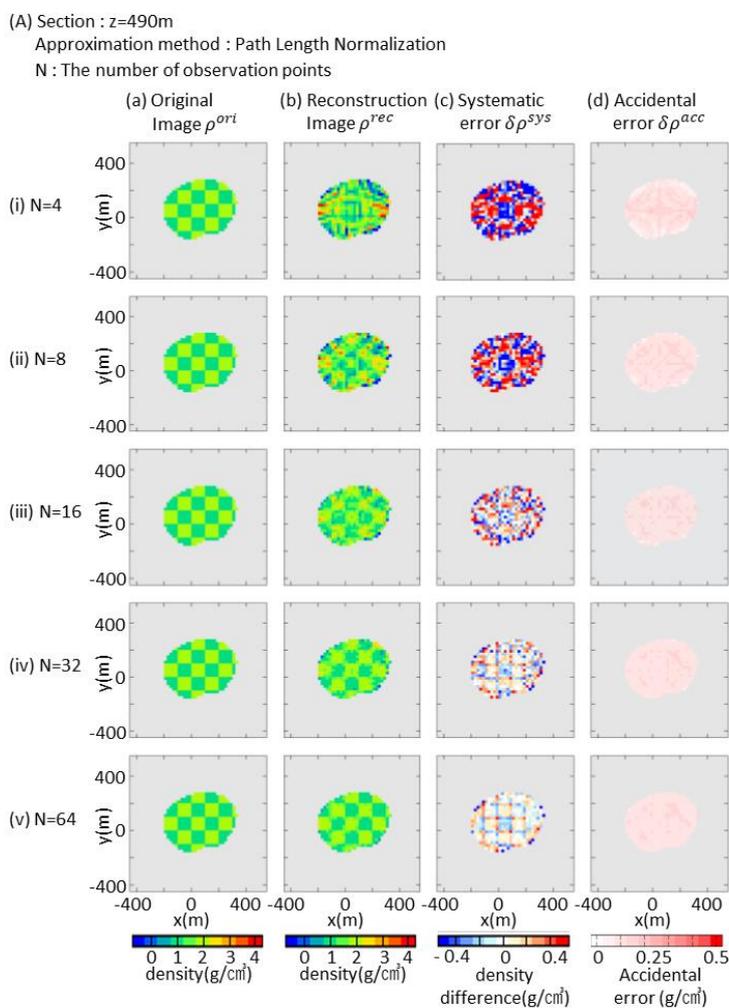
$$299 \quad \delta\rho^{acc}(x, y, z) = \frac{1}{J-1} \sqrt{\sum_{j=1}^J \{\delta\rho_j^{rec}(x, y, z) - \delta\rho^{rec}(x, y, z)\}^2}. \quad (5)$$

300 Figures 8A, 8B and 8C show the spatial distribution of the accidental errors. The
 301 accidental error did not depend on the location in the plane. The accidental error was
 302 smaller in a section with higher altitude, i.e., a section with a large elevation angle at
 303 observation. Moreover, we saw this trend regardless of the number of observation
 304 points.

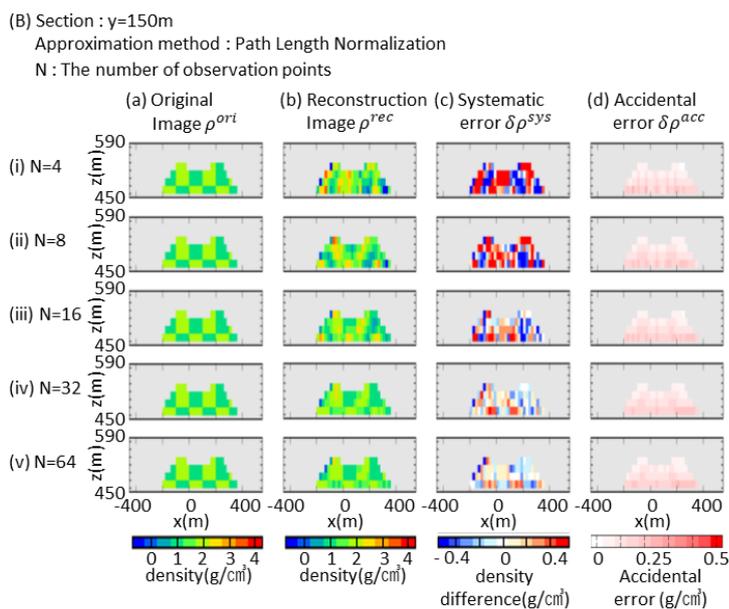
305 We defined the average of $\delta\rho^{acc}(x, y, z)$ over the entire object area as the average
 306 systematic error value μ^{acc} , and the sample standard deviation of $\delta\rho^{acc}(x, y, z)$ was
 307 taken as the accidental error distribution σ^{acc} . Even if the number of observation



308 points increased, no significant changes were observed in the accidental error.
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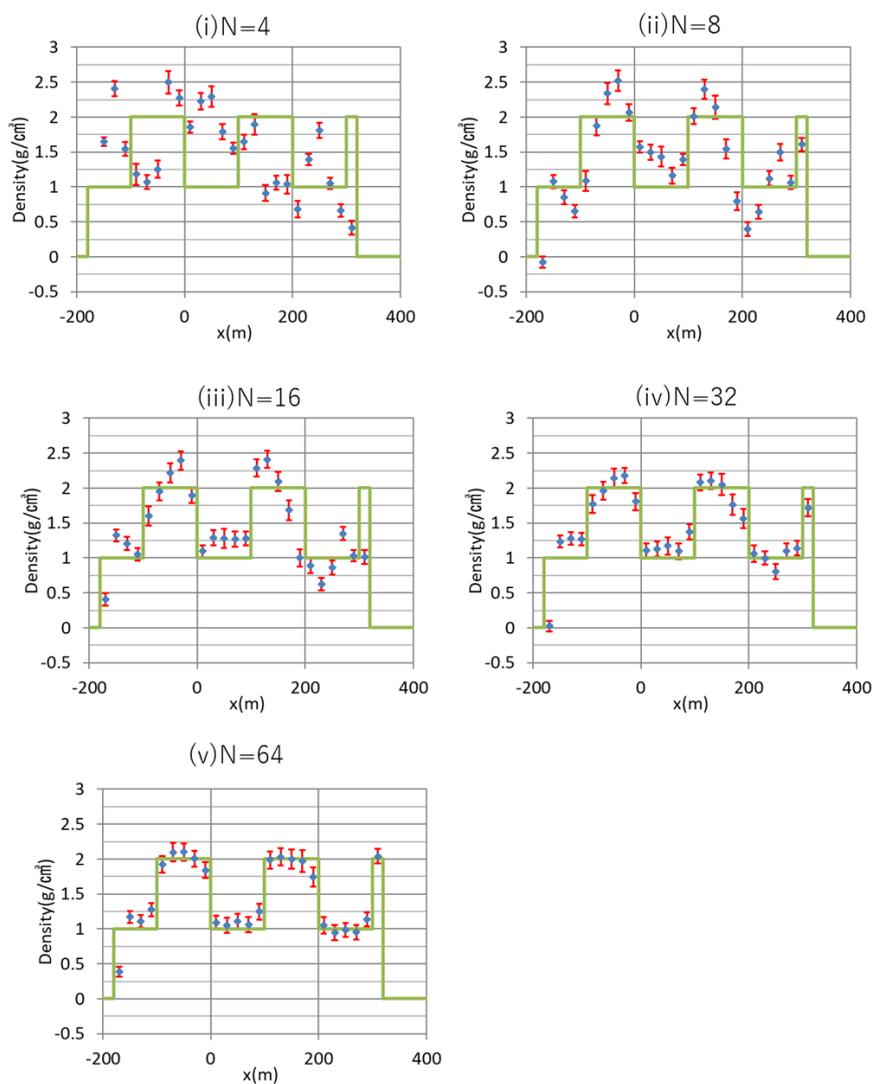
312
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 314 Figure 8:(A). Reconstruction results on a $z = 490\text{ m}$ cross section. (a) Original image:
 315 $\rho^{ori}(x, y, z)$; (b) reconstruction image: $\rho^{rec}(x, y, z)$; (c) systematic error: $\delta\rho^{sys}(x, y, z)$;
 316 Accidental error: $\delta\rho^{acc}(x, y, z)$.
 317



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319 Figure 8:(B). Reconstruction of results on a $y = 150\text{ m}$ cross section.

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321

322 Figure 8:(C). Reconstruction results across $z = 490$ m and $y = 150$ m cross sections.

323 The green lines represent the original image ($\rho^{ori}(x, y = 150, z = 490)$), the blue points

324 represent the reconstruction results with no accidental errors ($\rho^{rec}(x, y = 150, z = 490)$),

325 and the red error bar indicates the accidental errors ($\delta\rho^{acc}(x, y = 150, z = 490)$).

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327



328 Table 1: The relationship between the number of observation points and Systematic
 329 error deviation σ^{sys} (g/cm^3) and mean accidental error μ^{acc} (g/cm^3) on each “z” cross
 330 sections.

The number of observation points		450m	470m	490m	510m	530m	550m	570m
4	σ^{sys} (g/cm^3)	1.10	1.05	0.91	0.89	1.23	0.81	0.46
	μ^{acc} (g/cm^3)	0.23	0.15	0.11	0.07	0.04	0.02	0.01
8	σ^{sys} (g/cm^3)	0.74	0.73	0.65	0.59	0.75	0.48	0.36
	μ^{acc} (g/cm^3)	0.24	0.16	0.11	0.07	0.04	0.02	0.01
16	σ^{sys} (g/cm^3)	0.48	0.50	0.37	0.39	0.45	0.41	0.39
	μ^{acc} (g/cm^3)	0.24	0.16	0.11	0.07	0.04	0.02	0.01
32	σ^{sys} (g/cm^3)	0.35	0.33	0.25	0.27	0.33	0.42	0.37
	μ^{acc} (g/cm^3)	0.24	0.16	0.11	0.07	0.04	0.02	0.01
64	σ^{sys} (g/cm^3)	0.21	0.28	0.18	0.23	0.29	0.39	0.38
	μ^{acc} (g/cm^3)	0.24	0.16	0.11	0.07	0.04	0.02	0.01

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333 5 Discussion

334 A)

335 In Fig. 6, the systematic error does not converge to zero even if the number of
 336 observation points increases to more than 200. The observation point position β is
 337 represented by a counterclockwise rotation (see Fig. 1 definition of parameters). The
 338 interval of β is the angular resolution of the observation point. Increasing the number
 339 of observation points is equivalent to increasing the angular resolution of β . When
 340 comparing the resolution of X with the resolution of β for the 64-point observation, the
 341 resolution of β is $360/64 = 5.6^\circ$, the angular resolution is 2.3° , and the resolution of β
 342 is lower than X . However, for 256 points, the angular resolution of β is 1.4° , which is
 343 higher than the angular resolution of X . Figure 6 shows that the systematic error
 344 converges near the number of observation points when the resolution of β exceeds the
 345 resolution of X . These results indicate that the systematic error depends on the poor
 346 resolutions of both X and β .

347

348 B)

349 Why is the average systematic error value different between Feldkamp approximation



350 and path length normalization approximation? For a volcano with a structure similar to
351 Omuroyama, which is cone-shaped with a crater on the summit, the length of the muon
352 path and the elevation angle tend to be shorter than the path length estimated in the
353 horizontal plane (see Fig. 2). In path length normalization approximation, given that
354 the approximation is made with the path length as a reference, the difference in path
355 length is not important in Feldkamp approximation; however, the difference in path
356 length is not taken into consideration and is influenced by the change in the path length.
357 As a result, in Feldkamp approximation, the average value of the systematic error is
358 negative because of the presence of results with short path lengths.

359

360 C)

361 Why does the accidental error $\delta\rho^{acc}$ become smaller as the elevation section
362 increases? The accidental error $\delta\rho^{acc}$ occurs as a result of muon statistical error. The
363 muon statistical error follows a Poisson distribution. As the number of observed muons
364 increases, the muon statistical error becomes relatively small. On the other hand, the
365 muon flux increases as the elevation angle increases. In a section with high altitude, the
366 reconstruction calculation uses both data with a large elevation angle and data with a
367 large number of observed muons, thus reducing the accidental error.

368

369 D)

370 We performed these simulations under the condition that the total effective area of the
371 observation device is equal. For a 16-point observation, ST per point is $62.5 \text{ m}^2 \cdot \text{days}$;
372 for a 32-point observation, the device area S per point is two times greater at 31.25
373 $\text{m}^2 \cdot \text{days}$. Nevertheless, the results for the final accidental error values did not depend
374 on the number of observation points (see Table 1). In Equation (4), the operator is
375 $\sum_{n=1}^N$, where N is the number of observation points, and the factor $p_c(X_m, Z_{0n}, \beta_n)$
376 corresponds to the number of observed muons. p doubles if N is divided by two
377 because the effective area also doubles. As a result of the calculation, $\rho(x, y, z)$ in
378 Equation (4) remains the same for every x , y , and z value (i.e., each voxel). This is
379 why the accidental error is nearly identical between the 4-point observation and
380 64-point observation.

381 This discussion is able to apply for actual observation with any muon detector type. In
382 the case of emulsion type detector, it is easy to divide the effective area S . In the case of
383 hodoscope type detectors, we can divide the exposure period T by moving the detector
384 to another observation point (e.g. Tanaka, 2016).

385



386 E)

387 We summarized systematic error and accidental error for Omuroyama and $ST = 1000$
388 $\text{m}^2 \cdot \text{days}$ in Table 1. We can consider the better conditions of observation from this table.
389 In this table, systematic error is larger than accidental error excluding the case of 64
390 points and 450 m cross section. When the number of observation points is 4 to 32, $ST =$
391 $1000 \text{ m}^2 \cdot \text{days}$ is sufficient, but in the case of 64 points, it is better to use more ST .

392

393 F)

394 In this evaluation, the observation points were arranged on a circular orbit. In the
395 future, it is necessary to study more realistic observation point placements. For example,
396 it is difficult to put the observation points on the same plane or in same interval of β
397 because of topography. We should work these cases also as a next step.

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401

402 **6 Conclusion**

403 We simulated the systematic error of the 3D density structure of Omuroyama Volcano
404 by using several muon detectors via the FBP method with and without information on
405 mountain topography.

406

407 i) Systematic error which is defined as the density difference between the original and
408 reconstructed images in each voxel internal mountain depends on the angular
409 resolution of the muon detectors and the number of observation points.

410

411 ii) By comparing the systematic error with and without information on mountain
412 topography, the systematic error deviations are nearly identical. However, the mean
413 value of systematic error becomes more precise in the former case, i.e., the value is more
414 precise when a new method of approximation of path length normalization is used.

415

416 In addition, we studied the propagation of muon statistics to the final reconstruction
417 results. By assuming that the multiplication of total effective area and exposure period
418 is fixed and by changing only the number of observation points, the accidental error
419 caused by muon statistics does not change. This accidental error depends only on the



420 total muon statistics for all observation points.

421

422 Considering above, we established how to evaluate an observation plan of dozens of
423 muon radiographies.

424

425

426 **7 Future Prospects**

427 We assumed that there are 10s observation points in this study. The actual
428 observations, which involve many nuclear emulsion muon detectors, were executed by
429 Morishima et al. (2017). Furthermore, Olah et al. (2018) succeeded in developing a high
430 quality and inexpensive multiwire proportional chamber system. Considering such
431 recent advances, the CT volcanic observation of volcanoes by using numerous muon
432 detectors will be possible in the near future.

433

434

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